## High-Performance Gearheads for Servomotors Harmonic Planetary<sup>®</sup> HPN-A Right Angle Series





## Harmonic Planetary<sup>®</sup> HPN Series



HPN precision planetary gearheads are quiet, lightweight and compact with low cost and quick delivery.



HPN Planetary gearheads feature a robust design utilizing helical gears for quiet performance and long life. These gearheads are available with short lead times and are designed to couple to any servomotor with our Quick Connect<sup>®</sup> motor adaptation system. HPN gearheads are suitable for use in a wide range of applications for precision motion control and positioning. HPN Harmonic Planetary<sup>®</sup> gears are available in 5 sizes: 11, 14, 20, 32, and 40, with reduction ratios ranging from 3:1 to 50:1.

Low Backlash:
 Single Stage: < 6 arc minutes</li>
 Double Stage: < 9 arc minutes</li>
 High Efficiency
 Available Reduction Ratios: 3:1 to 50:1
 Helical Gearing
 Low Noise Design
 Smooth, High-Speed Transmission

Create a high-precision actuator by connecting any manufacturer's servomotor to our precision gearhead with Quick Connect<sup>®</sup> motor adaptation design.



### Application Examples







## Harmonic Planetary<sup>®</sup> **HPN Right Angle**



# HPN - 20 A - 15 - J6 RA2 - Motor Code

		······	<b>:</b>	····· ···	:	<u></u>
Model Name	Size	Design Revision	Reduction Ratio	Output Shaft Configuration	Right Angle Specification	Input Configuration
	11		4, 5, 7, 10		RA1	This and conversion the motor
HPN	14			J6: Shaft output with key and	RA1, RA2	mounting configuration If
Right Angle	20	А	3, 4, 5, 7, 10, 15, 20,	center tapped hole	RA2, RA3	unknown, substitute the motor
HarmonicPlanetary <sup>®</sup>	32		25, 30, 35, 40, 45, 50	tapped hole	RA3, RA4	model # and the motor code will
	40				RA4, RA5	be identified (or assigned).

### Figure 04-1 Input rotational direction Quick Connect<sup>®</sup> coupling Motor mounting flange Rubber cap ð Mounting pilot Oil seal on output side **Output rotational direction** Output shaft Mounting bolt hole

#### **Gearhead Construction**

### **Rating Table**

Please contact us if you have any questions about specifications and comparisons with other company's products.

Please con	lact us il you	i nave any c	questions about s	pecifications and	compansons with	i other companys	s products.		Table 05-1
Size	Number of	Ratio	Rated output torque *1 L10	Rated output torque *1 L50	Limit for repeated peak torque *2	Limit for momentary peak torque *3	Rated Input Speed (rpm) *4	Maximum Input Speed (rpm) *5	Backlash
	stages		N∙m	N∙m	N∙m	N∙m	rpm	rpm	arc-min
		4	9	14	14	40			<9
11.0	1	5	9	14	16	40	2000	10000	<8
		7	8	11	11	40	3000	10000	-7
		10	7	9	9	40			</td
		3	14	21	21	78			
		4	18	28	28	104			
	1	5	18	29	35	107			<6
		7	20	30	37	100			
		10	14	18	18	79			
		15	21	30	43	97			
14A		20	23	30	49	100	3000	6000	
		25	26	30	38	102			
	2	30	26	40	48	98			<9
		35	28	40	49	99			
		40	29	30	38	100			
		45	29	30	38	100			
		50	20	26	26	94			
		3	50	45	45	147			
	1	4	50	75	75	196			-6
		7	52	75	105	240			<0
		10	41	54	54	230			
		10	50	00 00	105	210			
204		20	66	80	140	256	3000	6000	
204		25	72	80	140	256	0000	0000	
		30	72	80	139	250			
	2	35	79	80	112	256			<9
		40	80	80	112	256			
		45	80	80	112	256			
		50	58	75	75	216			
		3	84	84	84	288			
		4	112	112	112	384			
	1	5	127	139	139	480			<6
		7	135	195	195	625			
		10	128	185	185	625			
		15	146	200	225	625			
32A		20	162	200	297	625	3000	6000	
		25	176	200	371	625			
	2	30	179	250	376	625			~9
	2	35	193	250	376	625			~5
		40	200	300	376	625			
		45	206	300	376	625			
		50	193	251	251	625			
		3	186	186	186	1,137			
		4	245	245	245	1,265			_
	1	5	298	310	310	1,265		5000	<6
		/	31/	430	430	829			
		10	302	480	509	829 1065			<u> </u>
40.4		10	342	417	41/	1200	2000		
40A		20	380	335	000	1107	3000		
		20	410 401	650	750	1265			
	2	35	452	700	752	1107		6000	<9
		40	468	700	752	1127			
		45	484	700	752	1 127			
		50	430	562	562	1,127			

\*1: Rated torque is based on life of 20,000 hours at max average input speed.
\*2: Limit for torque during start and stop cycles.
\*3: Limit for torque during emergency stops or from external shock loads. Always operate below this value.
\*4: Limit for sverage input speed during operation.
\*5: Maximum instantaneous input speed.

### Performance

Periorii	lance	,									Table 05-2
Size		11		14	20	32	40	14	20	32	40
Number of stages				1					2	2	
Reduction ratio	4	5	7, 10		3, 4, 5	, 7, 10		1	5, 20, 25, 30,	35, 40, 45, 5	D
Backlash arc min	<9	<8	<7		<	6			<	9	



### Dimensions

	A (H7)	в	с	D	E	Motor Shat F (I	it Diameter H7)	G	н	J	к	L	М	N	Mass
						Min	Max								(Kg)
Single Stage	Pilot Diameter <sup>*1</sup>	Pilot Bore Depth <sup>-1</sup>	Bolt Circle Diameter <sup>*1</sup>	Bolt Hole Thread and Depth <sup>-1</sup>	Input Flange Width (square) <sup>*1</sup>	8	8	Input Coupling Bore Depth <sup>-1</sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis⁺¹	Length Input Axis⁺¹	Length Output Axis⁺¹	95.7	74.4	0.95

Table 06-1



### **Dimensions**

															(Unit: mm)
	A (H7)	В	с	D	E	Motor Shat	't Diameter 17)	G	н	J	к	L	М	N	Mass (kq) *2
						Min	Max								
Single Stage	Pilot Diameter <sup>-1</sup>	Pilot Bore Depth <sup>-1</sup>	Bolt Circle Diameter <sup>-1</sup>	Bolt Hole Thread and Depth <sup>-1</sup>	Input Flange Width (square) <sup>*1</sup>	8	24	Input Coupling Bore Depth <sup>*1</sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis⁺¹	Length Input Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	119	89	2.1

\*1: Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request \*2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Table 07-1



### Dimensions

															(Unit: mm)
	A (H7)	В	с	D	E	Motor Sha F (	ft Diameter H7)	G	н	J	к	L	м	N	Mass (kg) *2
	$\checkmark$					Min	Max								( 3)
Double Stage	Pilot Diameter <sup>1</sup>	Pilot Bore Depth <sup>-1</sup>	Bolt Circle Diameter <sup>-1</sup>	Bolt Hole Thread and Depth <sup>*1</sup>	Input Flange Width (square) <sup>*1</sup>	8	24	Input Coupling Bore Depth <sup></sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	Length Input Axis <sup>-1</sup>	Length Output Axis <sup>*1</sup>	128.7 / 142	107.4 / 112	2.3

Table 08-1





### **Dimensions**

															(Unit: mm)
	A (H7)	в	с	D	E	Motor Sha F (	ft Diameter H7)	G	н	J	к	L	м	N	Mass (kg) *²
						Min	Max								
Single Stage	Pilot Diameter <sup>*1</sup>	Pilot Bore Depth <sup>*1</sup>	Bolt Circle Diameter <sup>*1</sup>	Bolt Hole Thread and Depth <sup>-1</sup>	Input Flange Width (square) <sup>-1</sup>	14	24	Input Coupling Bore Depth <sup>-1</sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	Length Input Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	158.9	115.1	5.8

\*1: Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request \*2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Table 09-1

Table 010-1



### **Dimensions**

$\backslash$		-				Motor Sha	ft Diameter								Mass
	A H7)	В	С	D	E	F (	H7)	G	н	J	к	L	м	N	(kg) *2
						Min	Max								
Double Stage	Pilot Diameter*1	Pilot Bore Depth <sup>-1</sup>	Bolt Circle Diameter <sup>-1</sup>	Bolt Hole Thread and Depth <sup>-1</sup>	Input Flange Width (square) <sup>*1</sup>	11	24	Input Coupling Bore Depth <sup>-1</sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	Length Input Axis <sup>-1</sup>	Length Output Axis <sup>•1</sup>	164.5	134.5	4.3



### **Dimensions**

ļ	חווס	ens	ions													Table 011-1 (Unit: mm)
		A (H7)	В	с	D	E	Motor Sha F (	ft Diameter H7)	G	н	J	к	L	м	N	Mass (kg) *2
ļ	$\sim$						Min	Max								
	Single Stage	Pilot Diameter <sup>*1</sup>	Pilot Bore Depth <sup>⁺1</sup>	Bolt Circle Diameter <sup>•1</sup>	Bolt Hole Thread and Depth <sup>-1</sup>	Input Flange Width (square) <sup>-1</sup>	14	35	Input Coupling Bore Depth <sup>-1</sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis*1	Length Input Axis*1	Length Output Axis⁺¹	209.5	152	15



Table 012-1



### **Dimensions**

															(Unit: mm)
		в		<b>_</b>	F	Motor Sha	ft Diameter		ц		K		54	N	Mass
	А (П7)	P				F (I Min	п7) Max	G		J	► ►	Ľ	IVI	N	(kg) *2
Double Stage	Pilot Diameter⁺¹	Pilot Bore Depth⁺¹	Bolt Circle Diameter <sup>*1</sup>	Bolt Hole Thread and Depth <sup>-1</sup>	Input Flange Width (square) <sup>*1</sup>	14	24	Input Coupling Bore Depth <sup>*1</sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	Length Input Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	221.6	177.8	11



### **Dimensions**

															(Unit: mm)
						Motor Sha	ft Diameter								Maaa
	A (H7)	В	С	D	E	F (I	H7)	G	н	J	К	L	м	N	Mass (kg) *2
						Min	Max								
Single Stage	Pilot Diameter <sup>*1</sup>	Pilot Bore Depth <sup>∹1</sup>	Bolt Circle Diameter <sup>-1</sup>	Bolt Hole Thread and Depth <sup>*1</sup>	Input Flange Width (square) <sup>+1</sup>	16	42	Input Coupling Bore Depth <sup>*1</sup>	Length Dimension Output Axis <sup>•1</sup>	Length Output Axis <sup>-1</sup>	Length Input Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	280.7	210.7	28

\*1: Dimensions for Quick Connect Adaptation Designs are tailored to the customer specified motor; detailed part #, drawings, and models furnished upon request \*2: The mass varies slightly depending on the reduction ratio and on the inside diameter of the input shaft coupling

Table 013-1





### **Dimensions**

	6112	10115	1												Table 014-1 (Unit: mm)
	A (H7)	в	с	D	E	Motor Sha F (	ft Diameter H7)	G	н	J	к	L	м	N	Mass (kg) *2
						Min	Max								(5)
Double Stage	Pilot Diameter*1	Pilot Bore Depth <sup>∹1</sup>	Bolt Circle Diameter <sup>*1</sup>	Bolt Hole Thread and Depth <sup>-1</sup>	Input Flange Width (square) <sup>-1</sup>	14	35	Input Coupling Bore Depth <sup>-1</sup>	Length Dimension Output Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	Length Input Axis <sup>-1</sup>	Length Output Axis <sup>-1</sup>	337	279.5	24

#### R 0 lanetary

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### **Technical Information**

Efficiency ...... 

### **Product Handling**

Ass	em	bly	<b>·</b> •	••	••	••	•••	•••	••	•••	• •	•••	•••	••	••	•••	••	•••	•••	••	• •	• 2	2
Lub	rica	atic	on	•••	• •	• •	•	•	•	• • •	• •	• •	•••	•••	•••		•••				•	• 2	24
War	ran	ty,	D	is	рс	sa	al	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••	•••		•••	•	2	25

The rated value and performance vary depending on the product series. Be sure to check the usage conditions and refer to the

items conforming to the related product.

### Efficiency

In general, the efficiency of a speed reducer depends on the reduction ratio, input rotational speed, load torque, temperature and lubrication condition. The efficiency under the following measurement conditions is plotted in the graphs on the next page.

The values in the graph are average values.

#### **Measurement Condition**

Measurement Condition			
Input speed	HPN: 3000rpm		
Ambient temperature	25°C		
Lubricant	Use standard lubricant. (See page 024 for details.)		

Input torque N·m

HPN Right Angle



Input torque N·m



#### Size 40A Gearhead





#### Input / Output Torque Diagram





Motor rpm ---- 1000rpm

— — -2000rpm

# Hamonic Plantens\* Technical Information

### **Output Shaft Bearing Load Limits**

HPN Series Output shaft load limits are plotted below.

HPN series uses radial ball bearings to support the output shaft. Please use the curve on the graph for the appropriate load coefficient (fw) that represents the expected operating condition.



Output shaft speed - 100 rpm, bearing life is based on 20,000 hours. The load-point is based on shaft center of radial load and axial load.

### Assembly

Assemble and mount your gearhead in accordance with these instructions to achieve the best performance. Be sure to use the recommended bolts and use a torque wrench to achieve the proper tightening torques as recommended in tables below.

#### **Motor Assembly Procedure**

To properly mount the motor to the gearhead, follow the procedure outlined below.

Turn the input shaft coupling and align the bolt head with the rubber cap hole.

#### **Optional Assembly Step for Improved Sealing**

Apply a sealant to the surface of the motor flange that will contact the gearhead mounting flange. (Recommended sealant: LOCKTITE 515)

With the speed reducer in an upright position as illustrated in the figure below, slowly insert the motor shaft into the coupling of speed reducer. Slide the motor shaft without letting it drop down. If the speed reducer cannot be positioned upright, slowly insert the motor shaft into the coupling of speed reducer, then tighten the motor bolts evenly until the motor flange and gearhead flange are in full contact. Exercise care to avoid tilting the motor when inserting it into the gearhead.

Fasten the motor and speed reducer flange with bolts.

Bolt*	tiahtenina toraue	
DOIL	ignicining torque	

Bolt* tightening torque Table 022-								Table 022-1	
Bolt size		M2.5	M3	M4	M5	M6	M8	M10	M12
Tightening torque	N∙m	0.59	1.4	3.2	6.3	10.7	26.1	51.5	89.9
	kgf∙m	0.06	0.14	0.32	0.64	1.09	2.66	5.25	9.17

Recommended bolt: JIS B 1176 Hexagon socket head bolt, Strength: JIS B 1051 12.9 or higher Caution: Be sure to tighten the bolts to the tightening torques specified in the table.

Tighten the input shaft coupling bolt to the recommended torque specified in the table below. The bolt(s) or screw(s) is (are) already inserted into the input shaft coupling when delivered. Check the bolt size on the confirmation drawing provided. Dolt\* tightonin

Bolt <sup>®</sup> tightening to	rque							Table 022-2
Bolt size		М3	M4	M5	M6	M8	M10	M12
	N∙m	2.0	4.5	9.0	15.3	37.2	73.5	128
lightening torque	kgf∙m	0.20	0.46	0.92	1.56	3.8	7.5	13.1
Caution: Always tighten the holts to the tightening targue specified in the table above. If the holts is not tightened to the targue value recommended singage of the motor								

shaft in the shaft coupling may result. The bolt size will vary depending on the size of the gear and the shaft diameter of the mounted motor. Check the bolt size on the confirmation drawing provided

#### · Insert the rubber cap provided. This completes the assembly.

Figure 022-1



Figure 023-1

#### Speed Reducer Assembly

No thread for eyebolt is provided because the mounting orientation varies depending on the customer's need. When mounting the reducer, hoist it using a sling paying extreme attention to safety.

When assembling gearheads into your equipment, check the flatness of your mounting surface and look for any burrs on tapped holes. Then fasten the flange (Part A in the diagram below) using appropriate bolts.

Bolt* tightening tor	que					Table 023-1					
0.		HPN									
Size		11	14	20	32	40					
Number of bolts		4	4	4	4	4					
Bolt size		M3	M5	M6	M8	M10					
Mounting PCD	mm	50	70	100	130	165					
Tinktoning to see	N∙m	1.4	6.3	10.7	26.1	51.5					
lightening torque	kgf∙m	0.14	0.64	1.09	2.66	5.26					
<b>-</b>	N∙m	27.9	110	223	528	1063					
Transfer torque	kgf∙m	2.85	11.3	22.8	53.9	108.5					

\* Recommended bolts: JIS B 1176 "Hexagon socket head bolts. "Strength classification 12.9 or higher in JIS B 1051.

#### Mounting the Load to the Output Shaft

When mounting a load onto the output shaft, take the specification of the output bearing into consideration.



#### Gearheads with an Output Shaft

Do not subject the output shaft to any impact when mounting a pulley, pinion and other parts. An impact to the output bearing will deteriorate the speed reducer precision and may cause reduced life or failure.

#### Lubrication

#### Prevention of Grease and Oil Leakage

- Only use the recommended greases.
- Provisions for proper sealing to prevent grease leakage are incorporated into the gearheads. However, please note that some leakage may occur depending on the application or operating condition. Discuss other sealing options with our applications engineers.
- When mounting the gearhead horizontally, position the gearhead so that the rubber cap in the adapter flange is facing upwards.

#### Sealing

• A double lip Teflon oil seal is used for the output shaft, gaskets or o-rings on all mating surfaces.

#### Lubricant

The standard lubrication for the HPN series is grease. All gearheads are lubricated at the factory prior to shipment and additional application of grease during assembly is not required. The gearheads are lubricated for the life of the gear and do not require re-lubrication.

High efficiency is achieved thorough the unique planetary gear design and grease selection.

#### Name of Lubricant

#### PYRONOC UNIVERSAL 0 Manufacturer: Nippon Oil Co.

Base oil: Rened mineral oil	Consistency: 375 at 25°C
Soap radical: Urea	Dropping point: 250°C or higher
Standard: NLGI No. 0	Product appearance: Light yellow

#### Ambient Operating Temperature Range: 0°C to +40°C

The lubricant may deteriorate if the ambient operating temperature is too high or too low. Please contact our sales office or distributor for operation outside of the ambient operating temperature range.

The temperature rise of the gear depends upon the operating cycle, ambient temperature and heat conduction and radiation as affected by the customers installation of the gear. A housing surface temperature of 70°C is the maximum allowable limit.

#### Warranty

Please contact us or visit our website at www.harmonicdrive.net for warranty details for your specific product.

#### Warranty Terms

All the products are warranted against defects in workmanship and materials for the warranted period. This limited warranty does not apply to any product that has been subject to:

- User's misapplication, improper installation, inadequate maintenance, or misuse.
- Disassembling, modification or repair by others than Harmonic Drive.

Our liability shall be limited exclusively to repairing or replacing the product only found by Harmonic Drive to be defective.

Harmonic Drive shall not be liable for consequential damages of other equipment caused by the defective products, and shall not be liable for the incidental and consequential expenses and the labor costs for detaching from and installing to the driven equipment.

#### Disposal

When disposing of the product, disassemble it and sort the component parts by material type and dispose of the parts as industrial waste in accordance with the applicable laws and regulations. The component part materials can be classified into three categories.

- Rubber parts: Oil seals, O-rings, rubber caps
- Aluminum parts: Housings, motor flanges
- Steel parts: Other parts

All efforts have been made to ensure that the information in this catalog is complete and accurate. However, Harmonic Drive LLC is not liable for any errors, omissions or inaccuracies in the reported data. Harmonic Drive LLC reserves the right to change the product specifications, for any reason, without prior notice. For complete details please refer to our current Terms and Conditions posted on our website.

### **Safety**



- In abitiant goal in you open you have a point you have not not in the matter with our the point open you have a point o
- If you swallowed it, you should immediately submit to medical treatment without throwing it up by constraint.

#### Please dispose as industrial waste.

Disposal

/!

Please dispose of the products as industrial waste when their useful life is over.

### Major Applications of Our Products



**Metal Working Machine** 



Processing Machine Tools



Measurement, Analytical and Test Systems



**Medical Equipment** 



Telescopes

Source: National observatory of Inter-University Research Institute Corporation



Space Flight Hardware

Rover image created by Dan Maas, copyrighted toCornell and provided courtesy NASA/ JPL-Caltech.



Robots



Energy Courtesy of Halliburton/Sperry Drilling Services













**Humanoid Robots** 

Source: Honda Motor Co., Ltd.



**Machine Tools** 



Aerospace





**Paper-making Machines** 





Flat Panel Display Manufacturing Equip.



**Optical Machines** 



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